

# \*P-Finsler spaces with vanishing Douglas tensor

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**Abstract.** The purpose of the present paper is to prove that a \*P-Randers space with vanishing Douglas tensor is a Riemannian space if the dimension is greater than three.

## 1. Introduction

Let  $F^n(M^n, L)$  be an  $n$ -dimensional Finsler space, where  $M^n$  is a connected differentiable manifold of dimension  $n$  and  $L(x, y)$  is the fundamental function defined on the manifold  $T(M) \setminus 0$  of nonzero tangent vectors. Let us consider a geodesic curve  $x^i = x^i(t)$ ,<sup>1</sup> ( $t_0 \leq t \leq t_1$ ). The system of differential equations for geodesic curves of  $F^n$  with respect to canonical parameter  $t$  is given by

$$\frac{d^2 x^i}{dt^2} = -2G^i(x, y), \quad y^i = \frac{dx^i}{dt},$$

where

$$G^i = \frac{1}{4} g^{ir} \left( y^s \left( \frac{\partial L_{(r)}^2}{\partial x^s} \right) - \frac{\partial L^2}{\partial x^r} \right),$$

$$g_{ij} = \frac{1}{2} L_{(i)(j)}^2, \quad (i) = \frac{\partial}{\partial y^i}, \quad \text{and} \quad (g^{ij}) = (g_{ij})^{-1}.$$

The Berwald connection coefficients  $G_j^i(x, y)$ ,  $G_{jk}^i(x, y)$  can be derived from the function  $G^i$ , namely  $G_j^i = G_{(j)}^i$  and  $G_{jk}^i = G_{j(k)}^i$ . The Berwald covariant derivative with respect to the Berwald connection can be written as

$$(1) \quad T_{j;k}^i = \partial T_j^i / \partial x^k - T_{j(r)}^i G_k^r + T_j^r G_{rk}^i - T_r^i G_{jk}^r.$$

(Throughout the present paper we shall use the terminology and definitions described in Matsumoto's monograph [6].)

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<sup>1</sup> The Roman indices run over the range  $1, \dots, n$ .

## 2. Douglas tensor, Randers metric, \*P-space

Let us consider two Finsler space  $F^n(M^n, L)$  and  $\overline{F}^n(M^n, \overline{L})$  on a common underlying manifold  $M^n$ . A diffeomorphism  $F^n \rightarrow \overline{F}^n$  is called geodesic if it maps an arbitrary geodesic of  $F^n$  to a geodesic of  $\overline{F}^n$ . In this case the change  $L \rightarrow \overline{L}$  of the metric is called projective. It is well-known that the mapping  $F^n \rightarrow \overline{F}^n$  is geodesic iff there exist a scalar field  $p(x, y)$  satisfying the following equation

$$(2) \quad \overline{G}^i = G^i + p(x, y)y^i, \quad p \neq 0.$$

The projective factor  $p(x, y)$  is a positive homogeneous function of degree one in  $y$ . From (2) we obtain the following equations

$$(3) \quad \overline{G}_j^i = G_j^i + p\delta_j^i + p_j y^i, \quad p_j = p_{(j)},$$

$$(4) \quad \overline{G}_{jk}^i = G_{jk}^i + p_j \delta_k^i + p_k \delta_j^i + p_{jk} y^i, \quad p_{jk} = p_{j(k)},$$

$$(5) \quad \overline{G}_{jkl}^i = G_{jkl}^i + p_{jk} \delta_l^i + p_{jl} \delta_k^i + p_{kl} \delta_j^i + p_{jkl} y^i, \quad p_{jkl} = p_{j(kl)}.$$

Substituting  $p_{ij} = (\overline{G}_{ij} - G_{ij}) / (n+1)$  and  $p_{ijk} = (\overline{G}_{ij(k)} - G_{ij(k)}) / (n+1)$  into (5) we obtain the so called Douglas tensor which is invariant under geodesic mappings, that is

$$(6) \quad D_{jkl}^i = G_{jkl}^i - (y^i G_{jk(l)} + \delta_j^i G_{kl} + \delta_k^i G_{jl} + \delta_l^i G_{jk}) / (n+1),$$

which is invariant under geodesic mappings, that is

$$(7) \quad D_{jkl}^i = \overline{D}_{jkl}^i.$$

We now consider some notions and theorems for special Finsler spaces.

**Definition 1.** ([1]) In an  $n$ -dimensional differentiable manifold  $M^n$  a Finsler metric  $L(x, y) = \alpha(x, y) + \beta(x, y)$  is called Randers metric, where  $\alpha(x, y) = \sqrt{a_{ij}(x)y^i y^j}$  is a Riemannian metric in  $M^n$  and  $\beta(x, y) = b_i(x)y^i$  is a differential 1-form in  $M^n$ . The Finsler space  $F^n = (M^n, L) = \alpha + \beta$  with Randers metric is called Randers space.

**Definition 2.** ([1]) The Finsler metric  $L = \alpha^2/\beta$  is called Kropina metric. The Finsler space  $F^n = (M^n, L) = \alpha^2/\beta$  with Kropina metric is called Kropina space.

**Definition 3.** ([1], [6]) A Finsler space of dimension  $n > 2$  is called  $C$ -reducible, if the tensor  $C_{ijk} = \frac{1}{2}g_{ij(k)}$  can be written in the form

$$(8) \quad C_{ijk} = \frac{1}{n+1} (h_{ij}C_k + h_{ik}C_j + h_{jk}C_i),$$

where  $h_{ij} = g_{ij} - l_i l_j$  is the angular metric tensor and  $l_i = L_{(i)}$ .

**Theorem 1.** ([7]) A Finsler space  $F^n$ ,  $n \geq 3$ , is  $C$ -reducible iff the metric is a Randers metric or a Kropina metric.

**Definition 4.** ([4], [5]) A Finsler space  $F^n$  is called \*P-Finsler space, if the tensor  $P_{ijk} = \frac{1}{2}g_{ij;k}$  can be written in the form

$$(9) \quad P_{ijk} = \lambda(x, y)C_{ijk}.$$

**Theorem 2.** ([4]) For  $n > 3$  in a  $C$ -reducible \*P-Finsler space  $\lambda(x, y) = k(x)L(x, y)$  holds and  $k(x)$  is only the function of position.

### 3. \*P-Randers space with vanishing Douglas tensor

**Definition 5.** ([3]) A Finsler space is said to be of Douglas type or Douglas space, iff the functions  $G^i y^j - G^j y^i$  are homogeneous polynomials in  $(y^i)$  of degree three.

**Theorem 3.** ([3]) A Finsler space is of Douglas type iff the Douglas tensor vanishes identically.

**Theorem 4.** ([5]) For  $n > 3$ , in a  $C$ -reducible \*P-Finsler space  $D_{jkl}^i = 0$  holds.

If we consider a Randers change

$$\bar{L}(x, y) \rightarrow L(x, y) + \beta(x, y),$$

where  $\beta(x, y)$  is a closed one-form, then this change  $\bar{L} \rightarrow L$  is projective.

**Definition 6.** ([1]) A Finsler space is called Landsberg space if the condition  $P_{ijk} = 0$  holds.

**Theorem 5.** ([2]) If there exist a Randers change with respect to a projective scalar  $p(x, y)$  between a Landsberg and a \*P-Finsler space (fulfilling the condition  $\bar{P}_{ijk} = p(x, y)\bar{C}_{ijk}$ ), then  $p(x, y)$  can be given by the equation

$$(10) \quad p(x, y) = e^{\varphi(x)}\bar{L}(x, y).$$

It is well-known that the Riemannian space is a special case of the Landsberg space. In a Riemannian space we have  $D_{jkl}^i = 0$ , and a  $\ast P$ -Randers space with a closed one-form  $\beta(x, y)$  is a Finsler space with vanishing Douglas tensor

**Theorem 6.** ([3]) *A Randers space is a Douglas space iff  $\beta(x, y)$  is a closed form. Then*

$$(11) \quad 2G^i = \gamma_{jk}^i y^j y^k + \frac{r_{lm} y^l y^m}{\alpha + \beta} y^i,$$

where  $\gamma_{jk}^i(x)$  is the Levi-Civita connection of a Riemannian space,  $r_{lm}$  is equal to  $b_{i;j}$  hence  $r_{lm}$  depends only on position.

From the Theorem 6. and (10) follows that

$$\frac{r_{lm} y^l y^m}{\alpha + \beta} = e^{\varphi(x)} (\alpha + \beta)$$

that is

$$\frac{r_{lm} y^l y^m}{\bar{L}} = e^{\varphi(x)} \bar{L}.$$

From the last equation we obtain

$$r_{lm} y^l y^m = e^{\varphi(x)} \bar{L}^2.$$

Differentiating twice this equation by  $y^l$  and  $y^m$  we get

$$b_{i;j} = e^{\varphi(x)} \bar{g}_{ij}.$$

This means that the metrical tensor  $\bar{g}_{ij}$  depends only on  $x$ , so we get the following

**Theorem.** *A  $\ast P$ -Randers space with vanishing Douglas tensor is a Riemannian space if the dimension is greater than three.*

#### 4. Further possibilities

From Theorem 1, Theorem 4 and our Theorem follows that only the  $\ast P$ -Kropina spaces can be  $\ast P$ - $C$  reducible spaces with vanishing Douglas tensor which are different from Riemannian spaces. We would like to investigate this letter case in a forthcoming paper.

## References

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